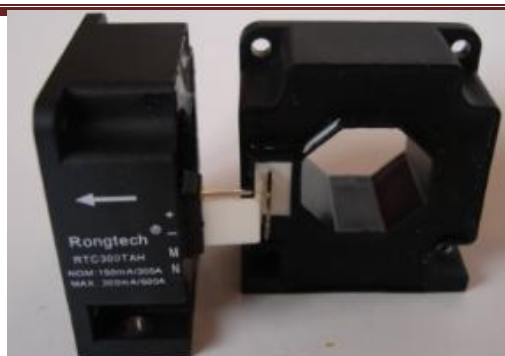


Rongtech Industry(ShangHai) Inc. ,

RTC300TAH Series High Precision Closed Loop Mode Hall Effect Current Sensor



Rongtech®



The RTC300TAH Series current sensor is a closed loop device based on the measuring principle of the hall effect and null balance method, with a galvanic isolation between primary and secondary circuit, the size of primary doesn't affect test precision, no matter the location of primary in the hole of current sensor, It can really measure resolution 1000:1 and it uses for precision measurement of DC, AC and pulse current.

Electrical data(Ta=25°C±5°C)					
Type Parameter	RTC50TAH	RTC100TAH	RTC200TAH	RTC300TAH	Unit
Rated current(Ipn)	5-50	10-100	20-200	30-300	A
Measure range(Ip)	150 (±18V, 80Ω)	300 (±18V, 30Ω)	700 (±18V, 18Ω)	900 (±18V, 2.0Ω)	A
Turnsratio(Np/Ns))	1:1000	1:1000	1:2000	1:3000	
Measure resister with ±12V	@50Amax 180(max)	@100Amax 75(max)	@200Amax 75(max)	@300Amax 5(max)	Ω
	@150Amax 40(max)	@300Amax 10(max)	@600Amax 5.0(max)	@600Amax 2(max)	Ω
Measure resister with ±15V	@50Amax 240(max)	@100Amax 110(max)	@200Amax 110(max)	@300Amax 82(max)	Ω
	@150Amax 60(max)	@300Amax 15(max)	@700Amax 10(max)	@750Amax 2(max)	Ω
Rated output (Isn)	5 (5A) - 50 (50A) ±0.2%	10 (10A) - 100 (100A) ±0.2%	10 (20A) - 100 (200A) ±0.2%	10 (30A) - 100 (300A) ±0.2%	mA
Coil resister	30	25	30	53	Ω
Supply voltage	±12~±18				V
Power consumption	≤20+IpX(Np/Ns)				mA
Offset current	@Ip=0	≤±0.2			mA
Offset drift	@ -40°C~85°C	±0.5			mA
Response time	@100A/μ S, 10%-90%	<1.0			us
Linearity	@Ip=0-±Ipn	≤0.1			%FS
Galvanic isolation	@ 50Hz, AC, 1min	3			KV
di/dt accurately followed		>100			A/μ s
Bandwidth	@ -3db	DC...100			KHz

Applications

1. Variable speed drives
2. Welding machine
3. Battery supplied applications
4. Uninterruptible Power Supplies (UPS)
5. Electrochemical

Standards

- UL94-V0. ;EN60947-1:2004 ;IEC60950-1:2001
- EN50178:1998 ;SJ 20790-2000

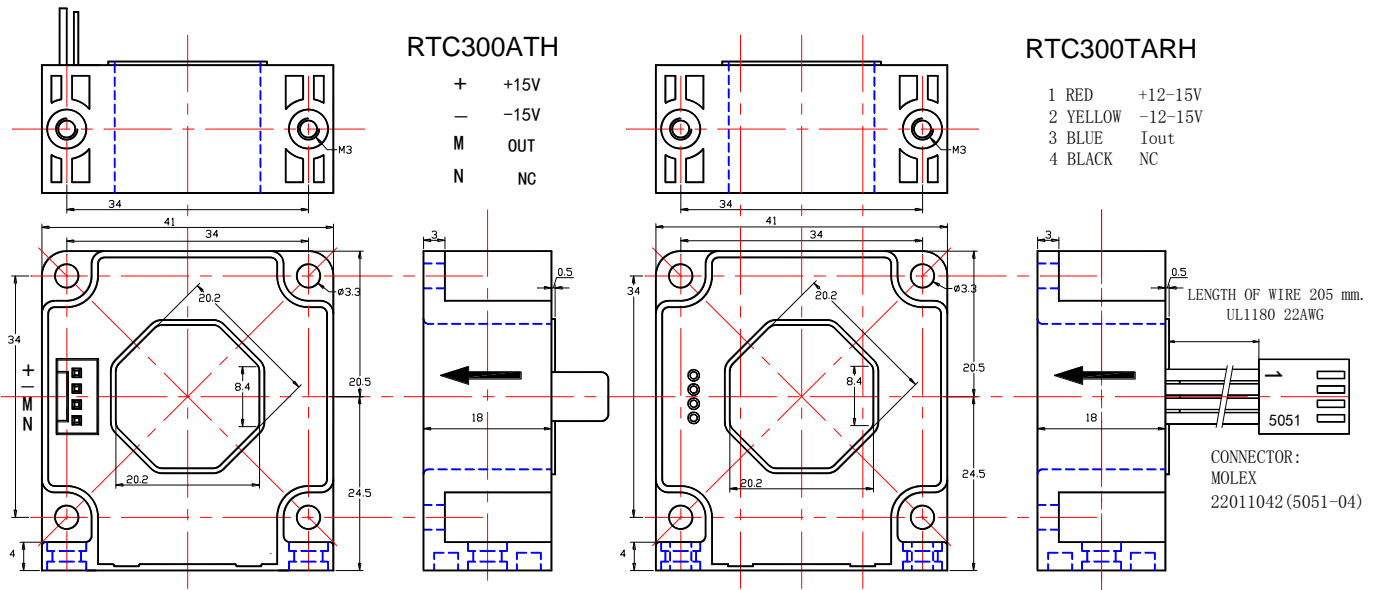
General date

	Value	Unit	Symbol
Operating temperature	-40 to +85	°C	TA
Storage temperature	-40 to +125	°C	TS
Mass (approx)	50	g	M

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Mechanical dimension (for reference only)



Remarks: 1. All dimensions are in mm. 2. General tolerance $\pm 1\text{mm}$

Directions for use

1. Is will be in a forward direction when the I_p flows according to the direction of the arrowhead.
2. The primary conductor should be $\leq 120^\circ\text{C}$.
3. The dynamic performance (di/dt and the response time) is the best when the primary hole is fully filled with the bus bar.
4. The primary turns should be at the top of the sensor for the best magnetic coupling.
5. When the current will be measured goes through a sensor, the voltage will be measured at the output end. (Note: The false wiring may result in the damage of the sensor).
6. Custom design in the different rated input current and the output current are available.

Characteristics chart

Pulse current signal response characteristic

Effects of impulse noise

